

What Is Claimed:

1. A manipulating hand for handling a wire material comprising
an elongate member having a longitudinal axis,
means for retaining said elongate member parallel to the forearm of an
operator,
a rod axially moveable with respect to said elongate member between an
extended position and a retracted position,
a hook at a distal end of said rod,
means for urging said rod to said extended position,
hand operable means for drawing said rod to said retracted position, and
an engagement member for engaging said hook when said hook is drawn
into said retracted position.

2. The manipulating hand of claim 1 wherein said means for retaining said
elongate member parallel to the forearm of an operator comprising a ring defining
a plane perpendicular to said axis.

3. The manipulating hand of claim 1 wherein said means for urging said
rod to said extended position is a coil spring.

4. The manipulating hand of claim 1 wherein said hand operable means
comprises a handle member perpendicular to said axis and a trigger moveable
by a finger of an operator having a hand on said handle.

5. The manipulating arm of claim 1 wherein said engagement member is a radial flange.

6. The manipulating hand of claim 1 wherein said elongate member is a tube and said rod is axially moveable within said tube.

7. The manipulating hand of claim 6 wherein said means for urging said rod to said extended position is a coil spring within said tube.

8. The manipulating hand of claim 7 wherein said hand operable means comprises a handle member perpendicular to said axis and a trigger moveable by a finger of an operator having a hand on said handle.

9. The manipulating hand of claim 8 wherein said trigger is locked for axial movement with said rod.

10. The manipulating hand of claim 8 and further comprising,
attachment means for locking said trigger for movement with said rod,
release means for releasing said attachment means from said rod wherein
said hook may be rotated about said axis while said attachment means is
released from said rod.

11. The manipulating hand of claim 10 wherein said means for retaining said elongate member parallel to the forearm of an operator comprises a ring defining a plane perpendicular to said axis through which said forearm of said operator extends.

12. A manipulating hand for handling a wire material comprising an elongate member having a longitudinal axis,

means for retaining said elongate member parallel to the forearm of an operator,

a hook and an engagement member at a distal end of said elongate member,

said hook moveable between a first position spaced from said engagement member and a second position abutting said engagement member,

means for urging said hook toward said first position, and

means for moving said hook from said first position to said second position wherein said means for moving is operable by the hand of an operator the forearm of which is retained parallel to said elongate member.